4th International Workshop on Domain-Specific Languages and models for ROBotic systems (DSLRob-13)

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Domain-Specific Languages (DSLs) and Model-driven Software Development (MDSD) are emerging areas of interest in the robotics research community. Both have been instrumental for resolving complex issues in a wide range of domains, including e.g. distributed and modular robotics, control, and vision.

The goal of this workshop is to bring together robotics researchers working with DSLs and models in different aspects of robotics.

The main objective of this workshop is a cross-pollination of ideas between robotics researchers in DSLs and models from different domains. DSLs and models are key elements in many robotic systems presented at leading conferences such as IROS and ICRA, but the domain-centric structure of the typical robotics conference does not offer a natural venue for exchange of ideas regarding DSLs and models.

The intended audience is those robotics researchers throughout the entire robotics community who use DSLs and models as a key component of their robotics software infrastructure. In addition, robotics researchers with an interest in modern approaches to solving complex software-related issues will find the workshop inspirational.
1st DSLRob 2010 at IROS 2010 (Taipei)
4 papers
DSLRob-13, Tokyo, Japan

2nd DSLRob 2011 co-located at IROS 2011 (San Francisco)
4 papers
3rd DSLRob 2012 at SIMPAR 2012 (Tsukuba)
6 papers
4th DSLRob 2013 co-located at IROS 2013 (Tokyo)
7 papers
This workshop will focus on the use of Domain-Specific Languages and Models for Robotic Systems. Topics that are of special interest include:

- domain-specific languages to express reactive behaviors, composition of behaviors, motion description languages (MDL),
- domain-specific languages to express uncertainty, modelling of physical system, real-time constraints,
- domain-specific languages to describe cooperative robotics and modular robotics systems,
- tools support and frameworks for describing and manipulating DSLs, models and meta-models for robotic systems,
- code generation and code transformation for robotics systems, variability in robotic systems,
- meta-models to express robotic specific structures and best practices,
- frameworks to combine DSLs in an uniform manner,
- benchmarks to compare use of DSL vs general-purpose programming, and
- programming languages in the context of robotic systems, visual languages for robots, languages to teach robotics.
Program committee

Alexandre Bergel, University of Chile, Chile
Geoffrey Biggs, AIST, Japan
Mirko Bordignon, Digipack Automation, Sanovo Technology Group
Herman Bruyninckx, University of Leuven, Belgium
Saadia Dhouib, CEA List, France
Hugo A. Garcia, University of Leuven, Belgium
Issa Nesnas, JPL Robotics, USA
Cyril Novales, PRISME, France
Jeff Gray, University of Alabama, USA
Henrik Nilsson, University of Nottingham, UK
Patrick Martin, York College of Pennsylvania, USA
Walid Taha, Halmstadt University, Sweden
Christina Vicente-Chicote, University of Extremadura, Spain
Mikal Ziane, LIP6, France
09:45 - 10:00  Welcome and Opening / Christian Schlegel, Serge Stinckwich
10:00 - 10:30  Selma Kchir, Tewfik Ziadi, Mika Ziane, Serge Stinckwich  
**A Top-Down Approach to Managing Variability in Robotics Algorithms**
10:30 - 11:00  Md. Abdullah Al Mamun, Christian Berger, Jorgen Hansson  
**Engineering the Hardware/Software Interface for Robotic Platforms: Comparison of Applied Model Checking with Prolog and Alloy**
11:00- 11:30  Yingfu Zeng, Chad Rose, Paul Brauner, Walid Taha, Jawad Masood, Roland Philippsen, Marcia O'Malley, Robert Cartwright  
**Modeling Basic Aspects of Cyber-Physical Systems, Part II**
11:30 - 13:15  LUNCH BREAK
13:15 - 13:45  Thomas Buchmann, Johannes Baumgartl, Dominik Henrich, Bernhard Westfechtel  
**Towards A Domain-specific Language For Pick-And-Place Applications**
13:45 - 14:15  Nico Hochgeschwender, Sven Schneider, Holger Voos, Gerhard K. Kraetzschmar  
**Towards a Robot Perception Specification Language**
14:15 – 14:45  Anders Lange, Anders Sorensen, Ulrik Schultz  
**Towards Automatic Migration of ROS Components from Software to Hardware**
14:45 – 15:15  Sebastian Blumenthal, Herman Bruyninckx  
**Towards a Domain Specific Language for a Scene Graph based Robotic World Model**
15:15 - 15:30  COFFEE BREAK
15:30- 17:00  DISCUSSION - roadmap (hot topics, priorities, benefits) of issues related to the WS topics
News

• community services
  • we now have a google-group: ras-tcsoft@googlegroups.com

• IROS 2013
  • organized session ”Software Engineering for Robotics”

• IROS 2013 Workshop Review => co-located to IROS

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Comments:
This workshop focuses on domain-specification language to model and control robots. The idea is to optimize the use of domain expert in domain-specified languages. Schedule of this workshop should be clarified.

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